



Modeling of Streetcar and Bus TSP in Toronto using Aimsun Microsimulation Software

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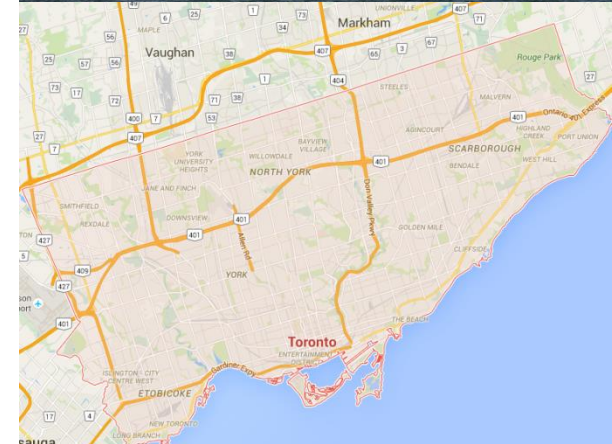
Outline

- Introduction
- Pilot Corridors
- Signals and TSP Algorithms
- API development for Aimsun
- Model Development in Aimsun
- Application within Aimsun

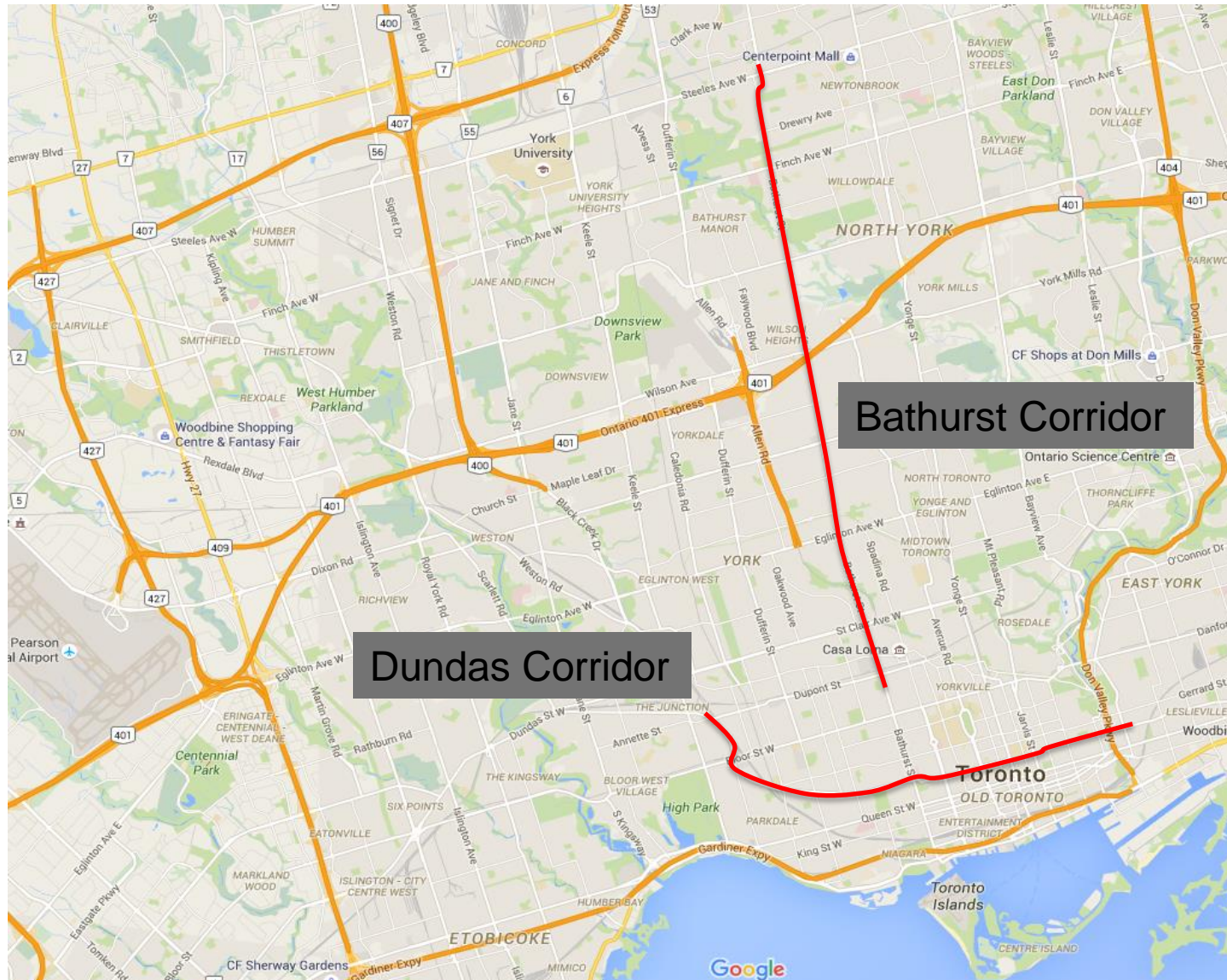
Introduction

The City of Toronto

- Approximately 2.8 million people
- Toronto Transit Commission (TTC) operates transit services - subways, LRTs, streetcars, buses, Wheel-Trans
- Annual TTC ridership of over 500 million trips on all transit modes
- 143 bus routes, 11 streetcar routes, 3 subway lines, 1 LRT



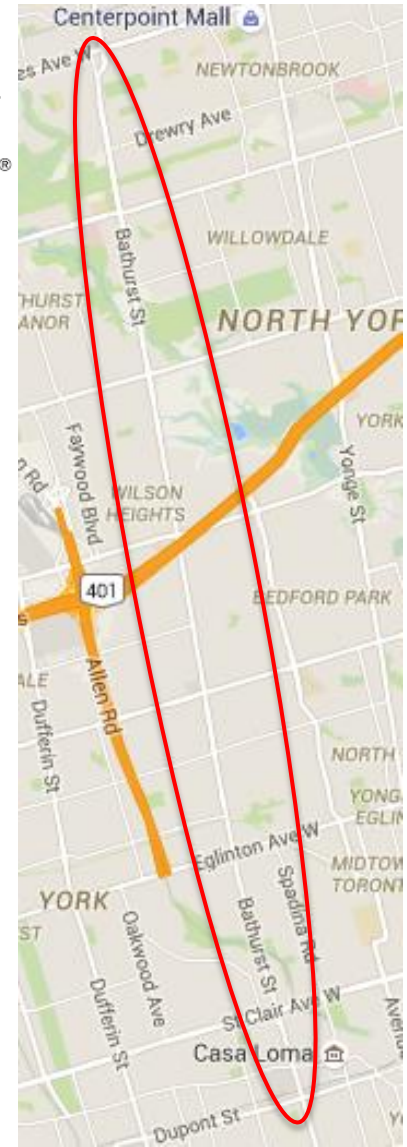
Pilot Corridors



Pilot Corridors

- Bathurst Street
 - Bus operations
 - 48 signals
 - 15 kilometer long N/S corridor
 - Several heavy pedestrian/car intersections
 - Team Lead - HDR

HDR | ONE COMPANY
Many Solutions®

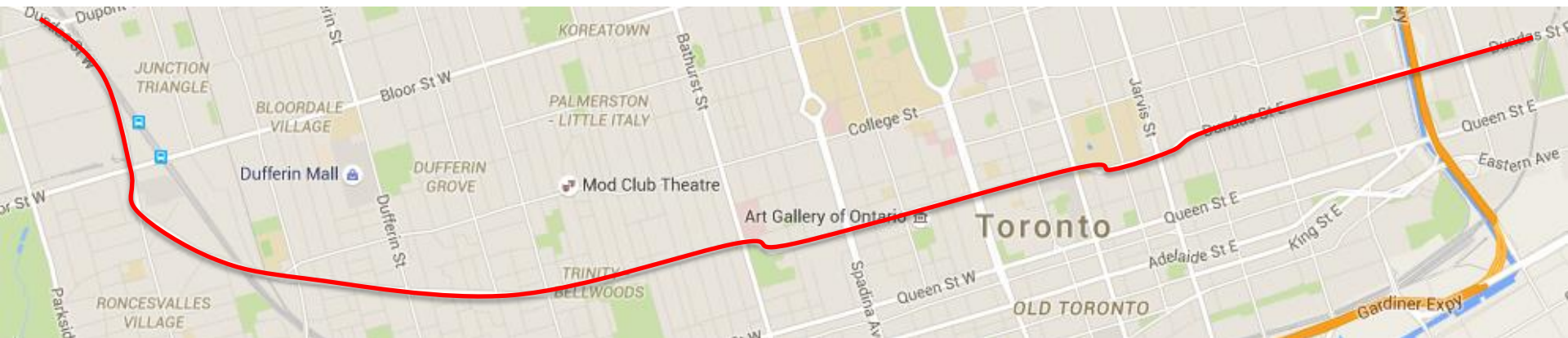


Pilot Corridors

- Dundas Street W
 - Streetcar operations
 - 37 signals
 - 10 kilometer long E/W corridor
 - Several heavy pedestrian/car intersections
 - Team Lead - IBI Group



IBI GROUP



Phase-Based Timing

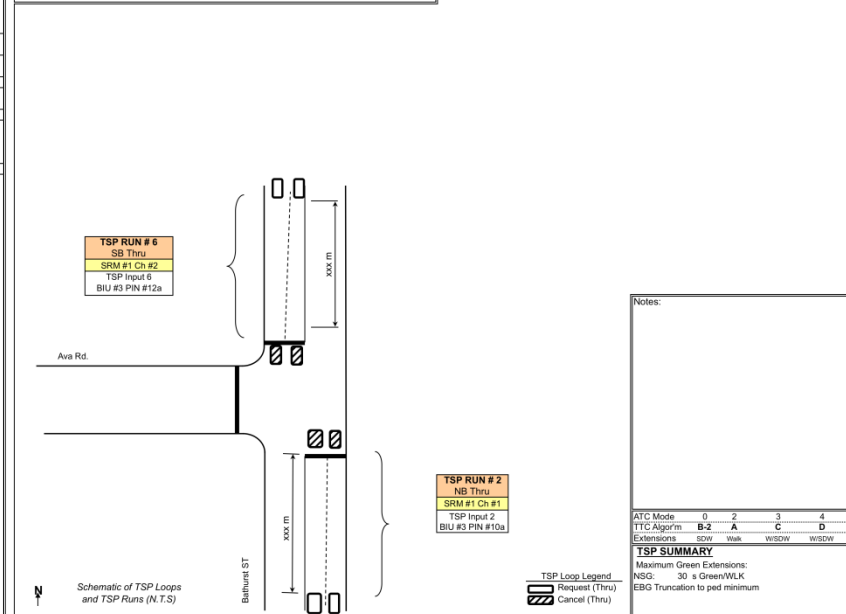
Page 1 – Basic

Page 2 – TSP

LOCATION: Bathurst St & Ava Rd		DISTRICT: Toronto & East York					
MODE/COMMENT: SA2-VMG with WRM, TSP & Jewish FXT Operation		COMPUTER SYSTEM: TransSuite					
PK: 505		CONTROLLER/CABINET TYPE: Peak ATC 1000 / TS2 T1					
PREPARED/CHECKED BY: CL/SL		CONFLICT FLASH: Red & Red					
PREPARATION DATE: April 25, 2014		DESIGN WALK SPEED: 1.0 m/s (FDW based on full crossing at 1.2 m/s)					
IMPLEMENTATION DATE: April 28, 2014		CHANNEL DROP: 4019/21					
NEMA Phase	Phase Mode (Fixed/Demanded or Callable)	Remarks					
		OFF	AM	PM	J. SABB-AM	J. SABB-PM	J. SABB-OFF
Local Plan Split Table	Pattern 1	Pattern 2	Pattern 3	Pattern 4	Pattern 5	Pattern 6	
1 NOT USED							
2 Bathurst St ↑	Fixed POZ activated by Request Loop (max extension of 30 secs in Green/Walk)						
3 NOT USED							
4 Ava Rd ↔	Callable by Stopbar loop and/or Pushbutton; Extendable by Stop bar loop						
5 NOT USED							
6 Bathurst St ↓	Fixed POZ activated by Request Loop (max extension of 30 secs in Green/Walk)						
7 NOT USED							
8 NOT USED							
CL		90	90	90	90	90	90
OF		27	59	79	59	79	27

NOTE: Ava Rd. is one-way Eastbound.
Jewish High Holidays schedule 2014 updated on Feb 28, 2014 and implemented on Mar 21, 2014
Picked up system control on April 29, 2014

LOC: Bathurst St & Ava Rd		PREPARATION DATE (TIMING CARD): April 25, 2014	
MODE: SA2-VMG with WRM, TSP & Jewish FXT Operation		PK: 505	
OFFSET CORRECTION PARAMETERS			
2.3.4 O.C. Extend / Reduce (Max. time added & subtracted in sec.)			
From page 1			
2.3.2 x O.C. (Cycle) (Sec)			
Thrus: Pattern 1			
2.3.3 Transit Run Parameters			
ATC Green Extend Mode (Equivalent TTC Algorithm) Mode 2 A Mode 2 A			
2.3.3 Transit Action Plan 1 (Used for all Patterns)			
Run Enable (n = Yes) X X			
Run Config = 1 Recovery = 2 (O.C. with delay)			
2.3.4 Transit Run Configuration 1			
Delay / Extend / Fail -- / - / 235 - / - / 235			
CALLS (and Extends) -- 2/6 -- 2/6			
Skips -- --			
Reduces (Truncates) -- 4/8 -- 4/8			
2.3.6 TSP Split Tables: 1, 2, 3, 4, 5 & 6			
GRN EXT (SDW Extension) -- -- -- -1 -- -- -- -1			
GRN RDC (Reduction) -- -- -- -1 -- -- -- -1			
WLK EXT (Walk Extension) -- 30 -- -- -- 30 -- --			



Toronto's TSP Operations

- Active Priority Control Strategy
 - Priority given to transit vehicle following detection
 - Detection via transit loops
- Unconditional Priority Requests
 - First Sequenced, First Serve
- Generally PEEK ATC-1000 controllers
 - Other NEMA controllers for special cases

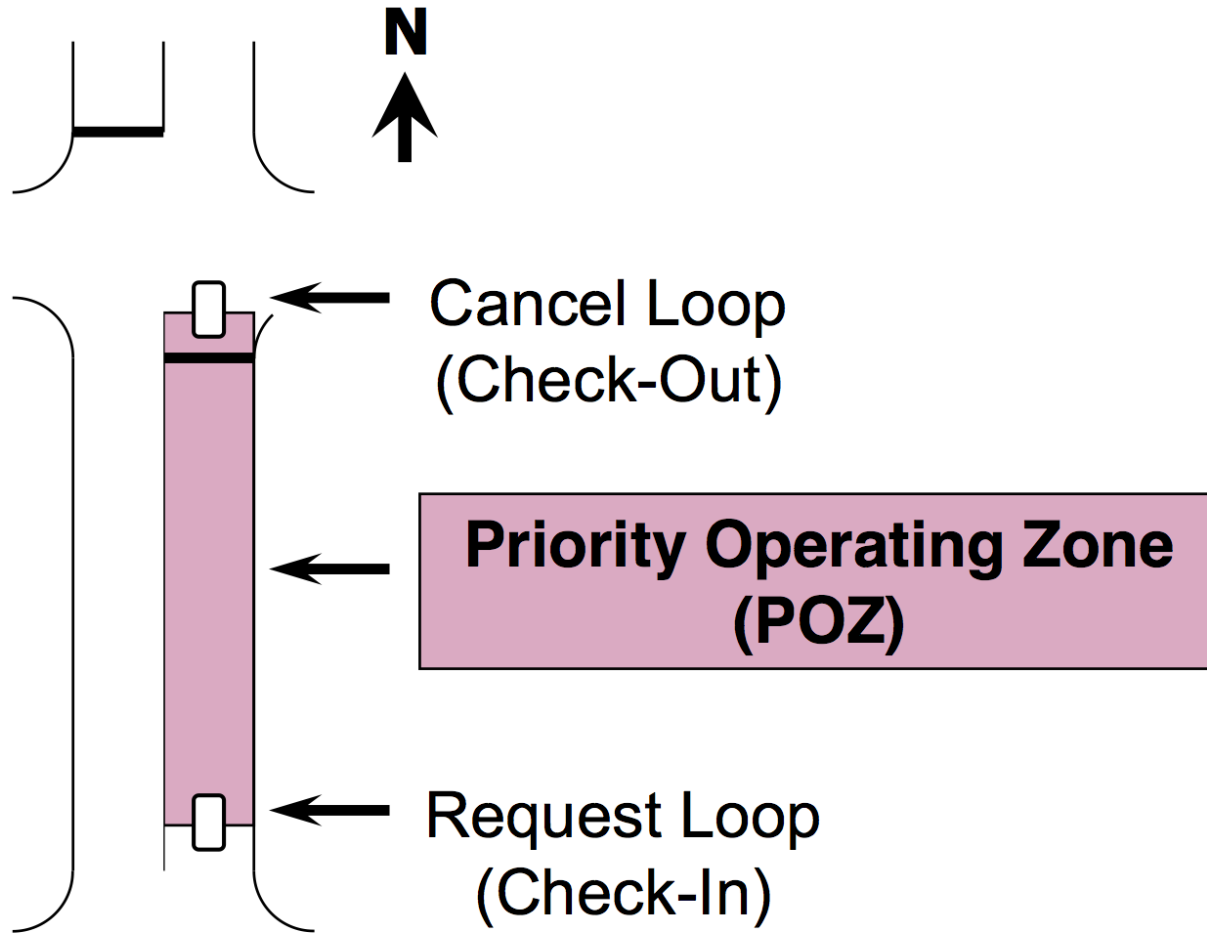
Overview of TSP Features

- Existing TSP Features
 - Green Extension
 - All Direction Transit Priority
 - Phase Truncation (i.e. Early Green)
 - Call/Extend Special Transit Phases
 - Multiple TSP Opportunities per cycle
 - Shifting and skipping phases
- Recovery after TSP
 - Offset Correction
 - Adverse effect on signal coordination

Extension Algorithms

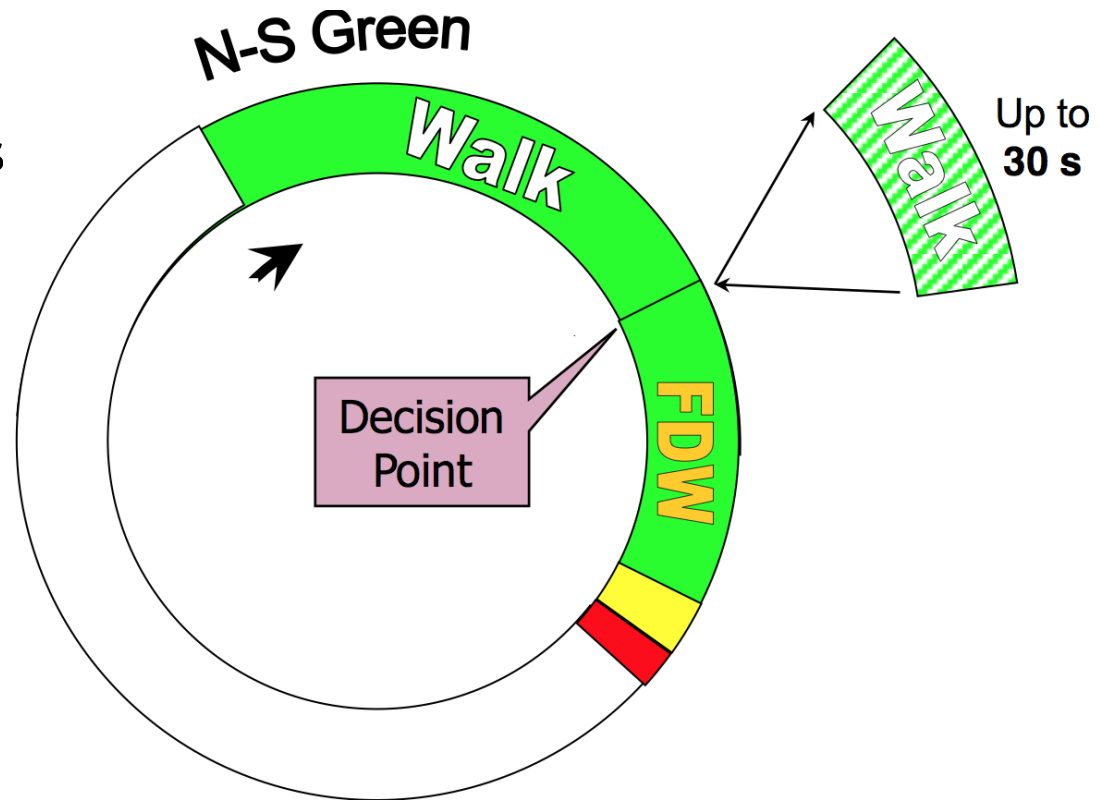
- Current green extension algorithms (included in pilot projects)
 - Algorithm “A”: Green/Walk extension
 - Algorithm “B”: Green/SDW extension
- Enhanced Algorithms
 - Algorithm “C” included as part of pilot
 - Algorithm “D” not included

Green Extension



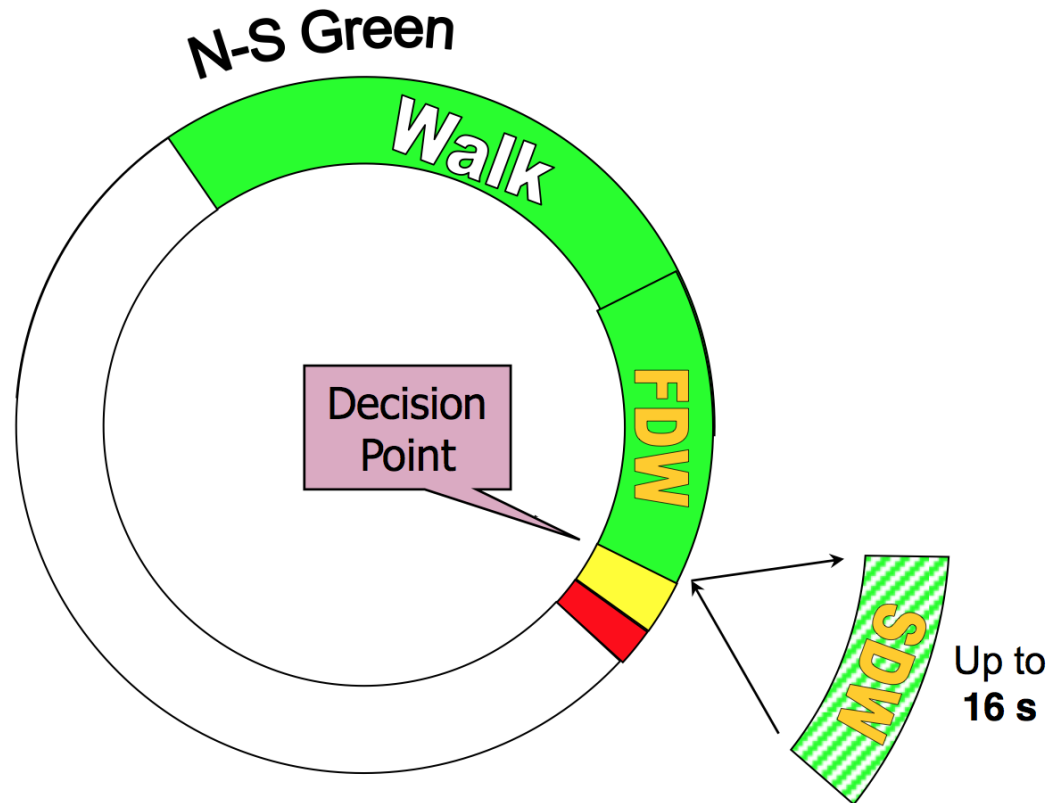
Algorithm A

- Advantages
 - Few Failed Extensions (30 s max.)
 - More pedestrian friendly
- Disadvantages
 - Less Efficient signal operation (with longer FDW, City provides full clearance in FDW)
 - Not practical everywhere



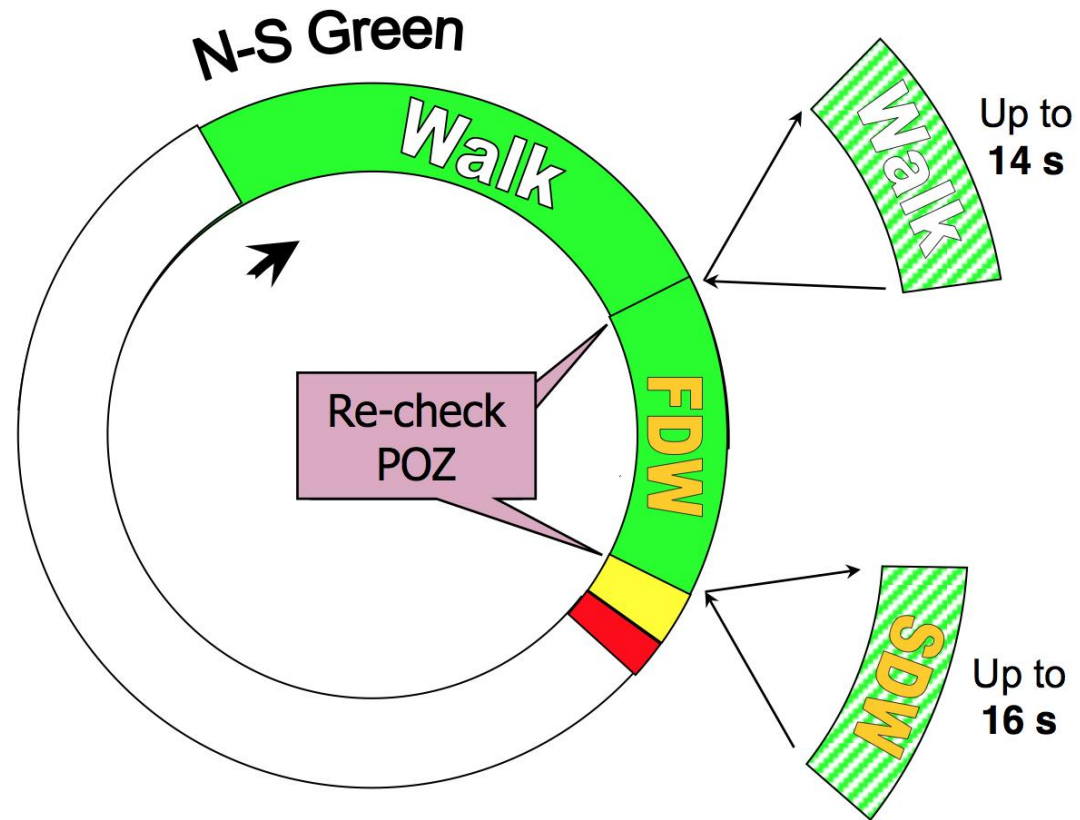
Algorithm B

- Advantages
 - Efficient Signal operation
 - Practical with closely spaced signals
- Disadvantages
 - More Failed extensions (16 s max.)
 - Less pedestrian friendly



Algorithm C

- Advantages
 - Fewer Failed extensions
 - Improved efficiency (w.r.t. “A”)
 - More pedestrian friendly than “B”
- Disadvantages
 - Less efficient than “B”
 - Not practical everywhere

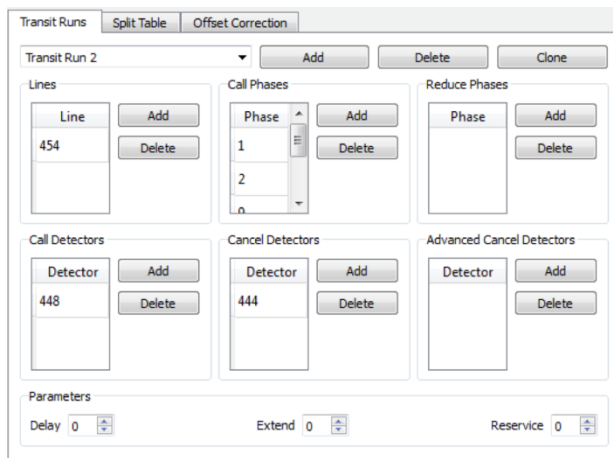


Modeling challenges

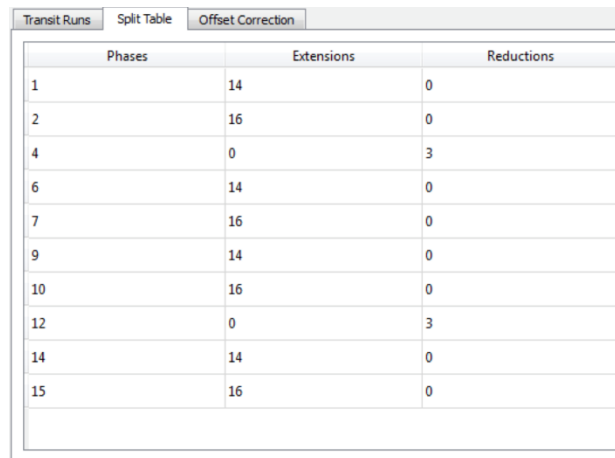
- Emulate the operation of the real signal controller
 - Basic operation
 - FXT, SAP, SA2
 - TSP operation
 - Algorithm A, Algorithm B, Algorithm C
- Emulate the operation of the real detectors
- Model the rules of road around the streetcar

Modeling the signal controllers

- Standard NEMA controller for basic operation
- Customized API to handle changes with TSP calls
- Customized UI to input TSP parameters

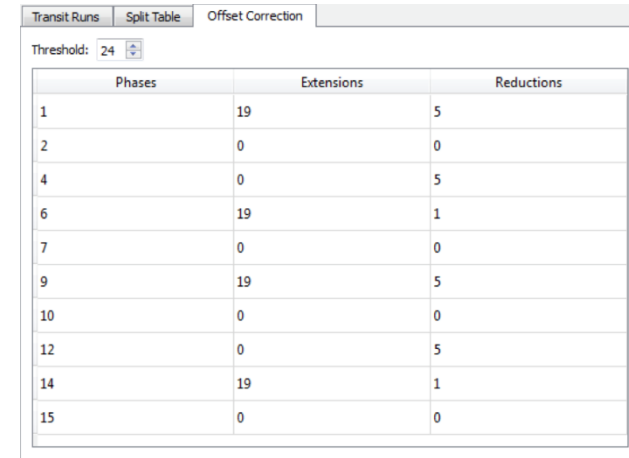


Transit Run Attributes



Phases	Extensions	Reductions
1	14	0
2	16	0
4	0	3
6	14	0
7	16	0
9	14	0
10	16	0
12	0	3
14	14	0
15	16	0

Phase Split Attributes

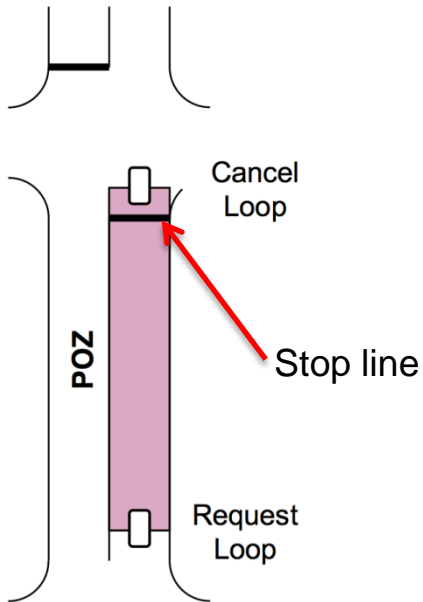


Phases	Extensions	Reductions
1	19	5
2	0	0
4	0	5
6	19	1
7	0	0
9	19	5
10	0	0
12	0	5
14	19	1
15	0	0

Phase Offset Correction Attributes

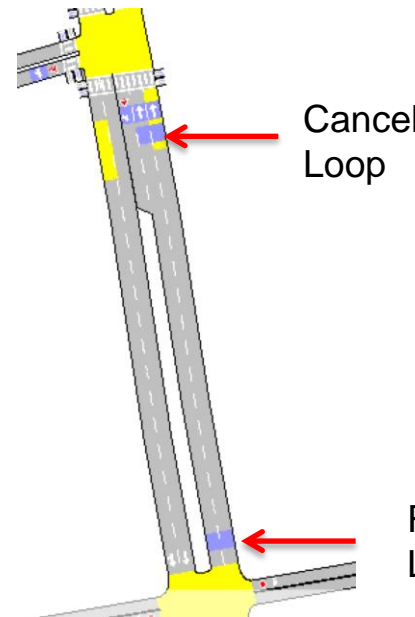
Modeling the detectors

- Real World Placement



- Model Placement

- Offset needed to place detector beyond the stop line



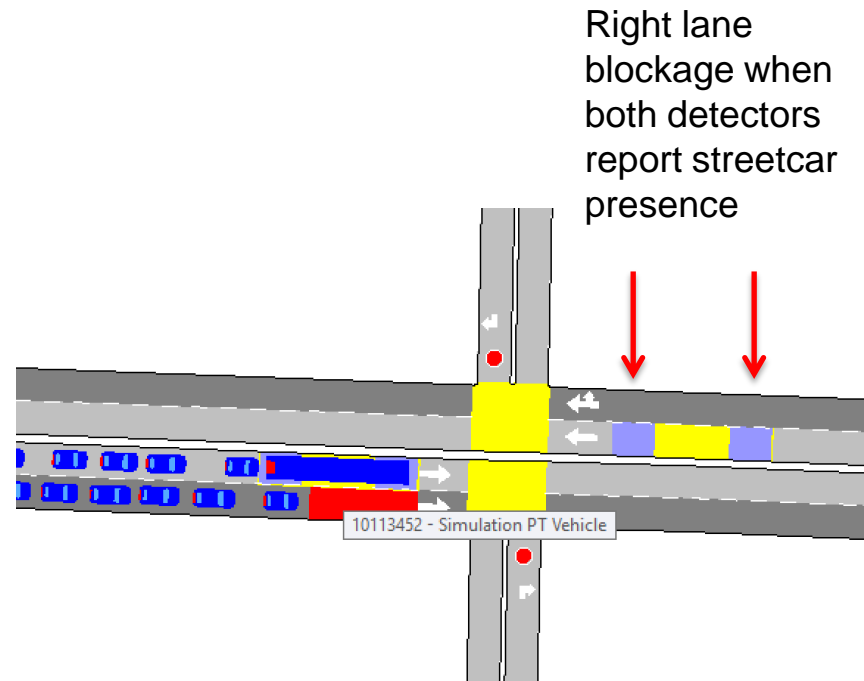
Detector: 8637 (Layer: Bathurst_model_network_ver6_clark)

Name	Value
OSM Group	undefined
OSM Type	unclassified
Position Offset	18.0000
Presence - SI - Last Generated - 2602	No

Request Loop

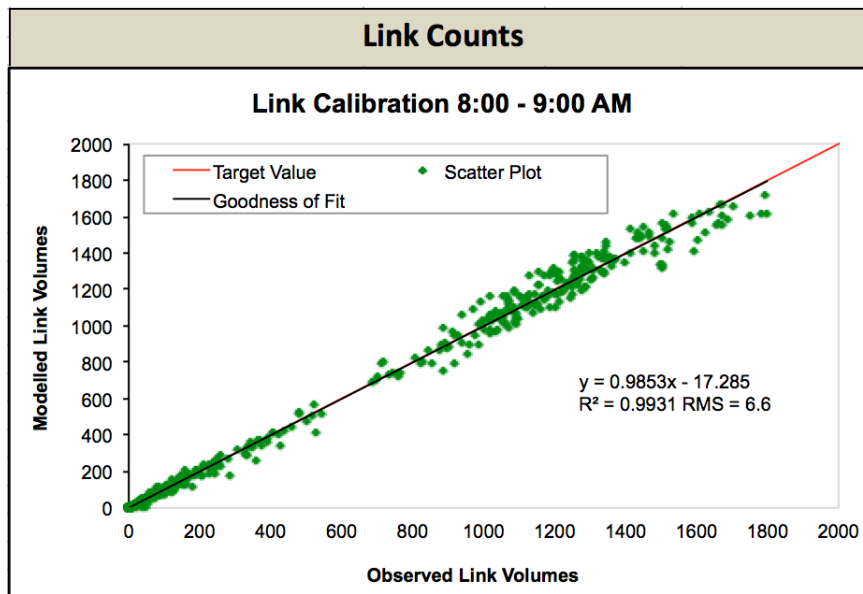
Modeling the rules of road

- Private vehicles cannot overtake when the doors of the streetcar are open

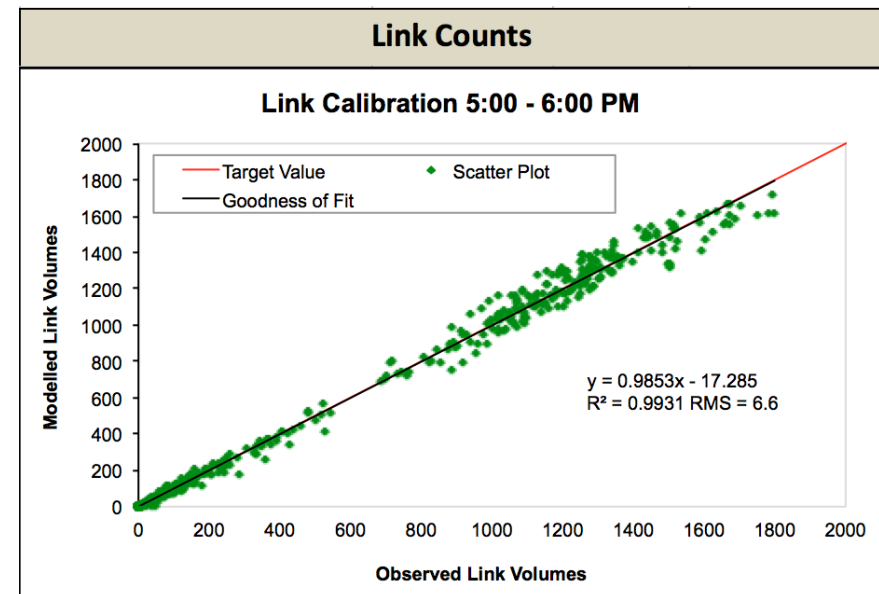


Model Calibration

- Modeled Section Flows - Bathurst



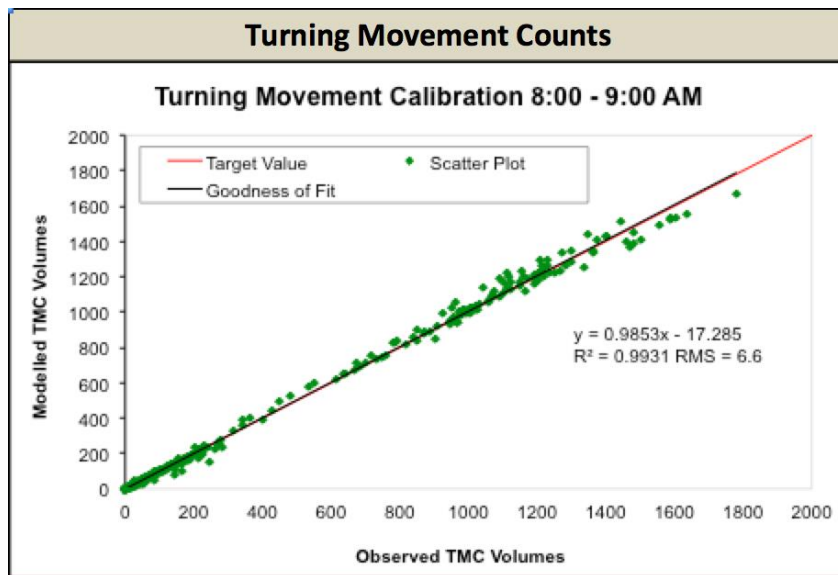
Link Calibration Check 8:00-9:00 AM			
Peak Direction	Modelled	Target	Check
Percentage of Links with GEH <= 5	100%	85%	OK
Percentage of Links with GEH <= 10	100%	95%	OK
Percentage of Links with GEH > 10	0%	5%	OK
RMSE	8%	30%	OK
Sum of All Link Flows within 5% of sum of	100%	95%	OK
Corridor Screenline Volumes Within 15%	100%	100%	OK



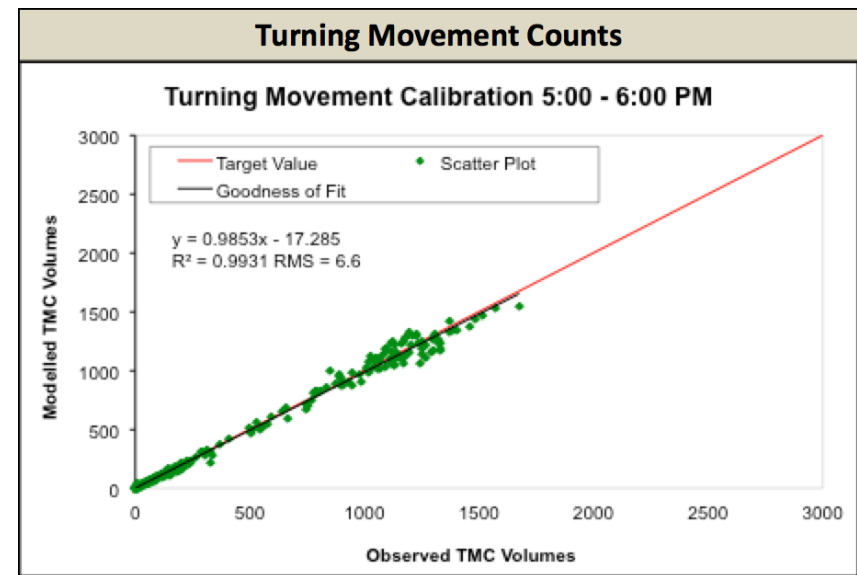
Link Calibration Check 5:00-6:00 PM			
Peak Direction	Modelled	Target	Check
Percentage of Links with GEH <= 5	100%	85%	OK
Percentage of Links with GEH <= 10	100%	95%	OK
Percentage of Links with GEH > 10	0%	5%	OK
RMSE	8%	30%	OK
Sum of All Link Flows within 5% of sum of	100%	95%	OK
Corridor Screenline Volumes Within 15%	100%	100%	OK

Model Calibration

- Modeled Turn Flows - Bathurst



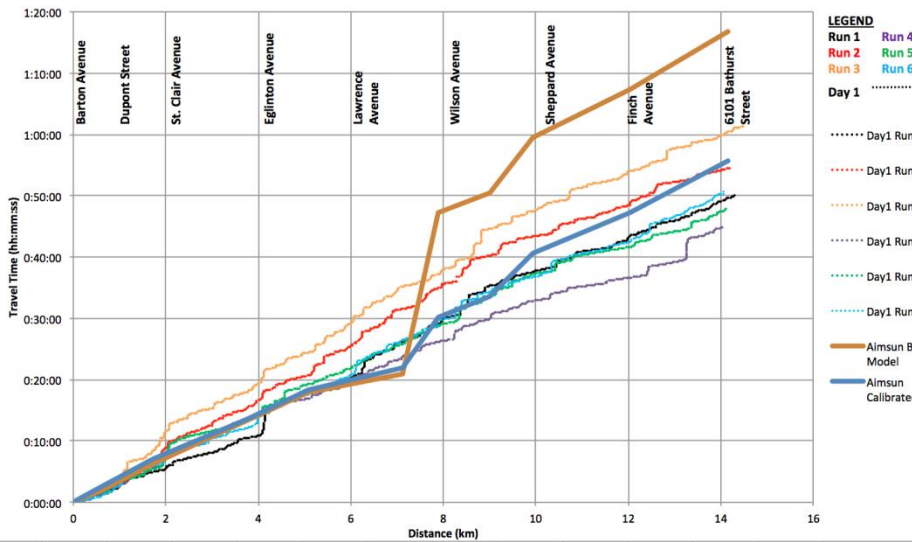
TMC Calibration Check			
Peak Direction	Modelled	Target	Check
Percentage of Links with GEH <= 5	99%	85%	OK
Percentage of Links with GEH <= 10	100%	95%	OK
Percentage of Links with GEH > 10	0%	5%	OK
RMSE	8%	30%	OK



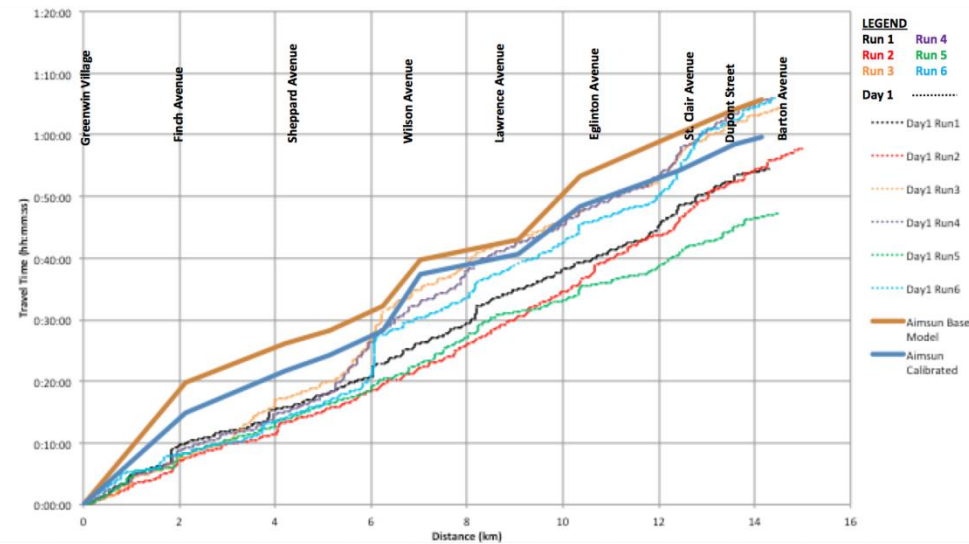
TMC Calibration Check			
Peak Direction	Modelled	Target	Check
Percentage of Links with GEH <= 5	99%	85%	OK
Percentage of Links with GEH <= 10	100%	95%	OK
Percentage of Links with GEH > 10	0%	5%	OK
RMSE	7%	30%	OK

Model Calibration

- Modeled Transit Travel Times- Bathurst AM



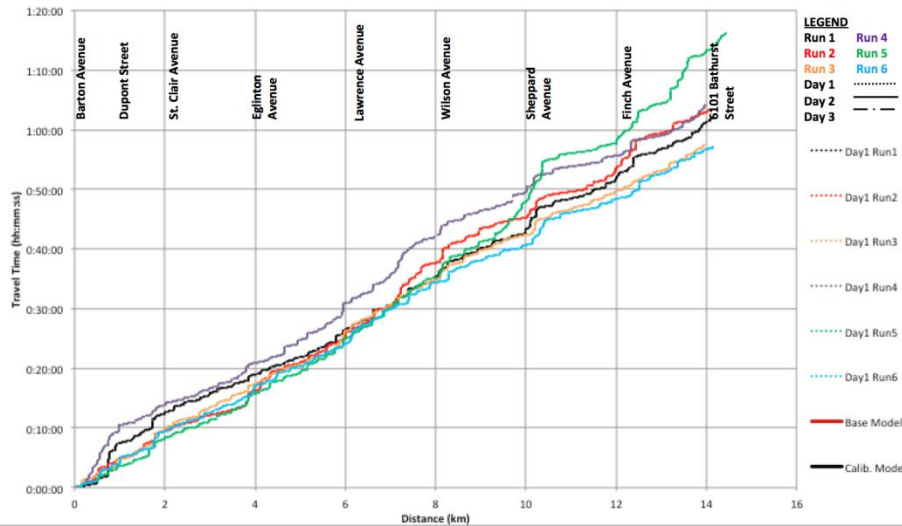
Northbound



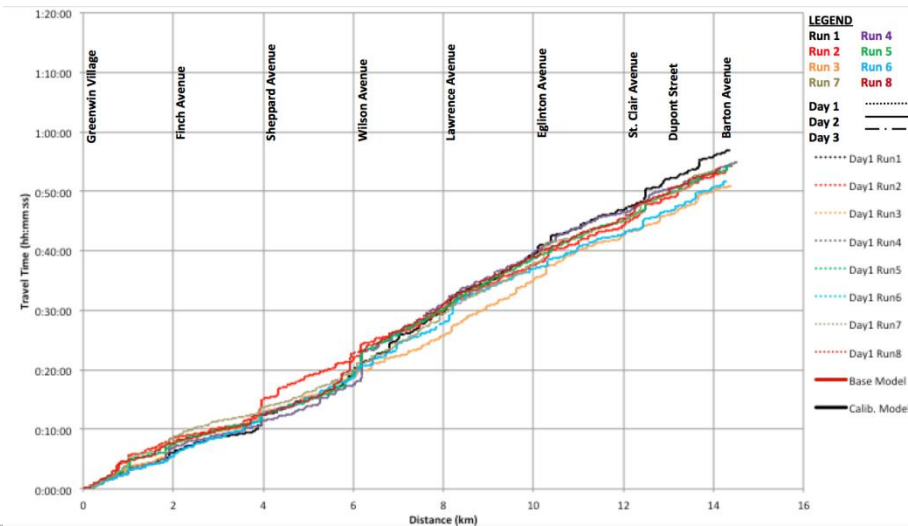
Southbound

Model Calibration

- Modeled Transit Travel Times- Bathurst PM

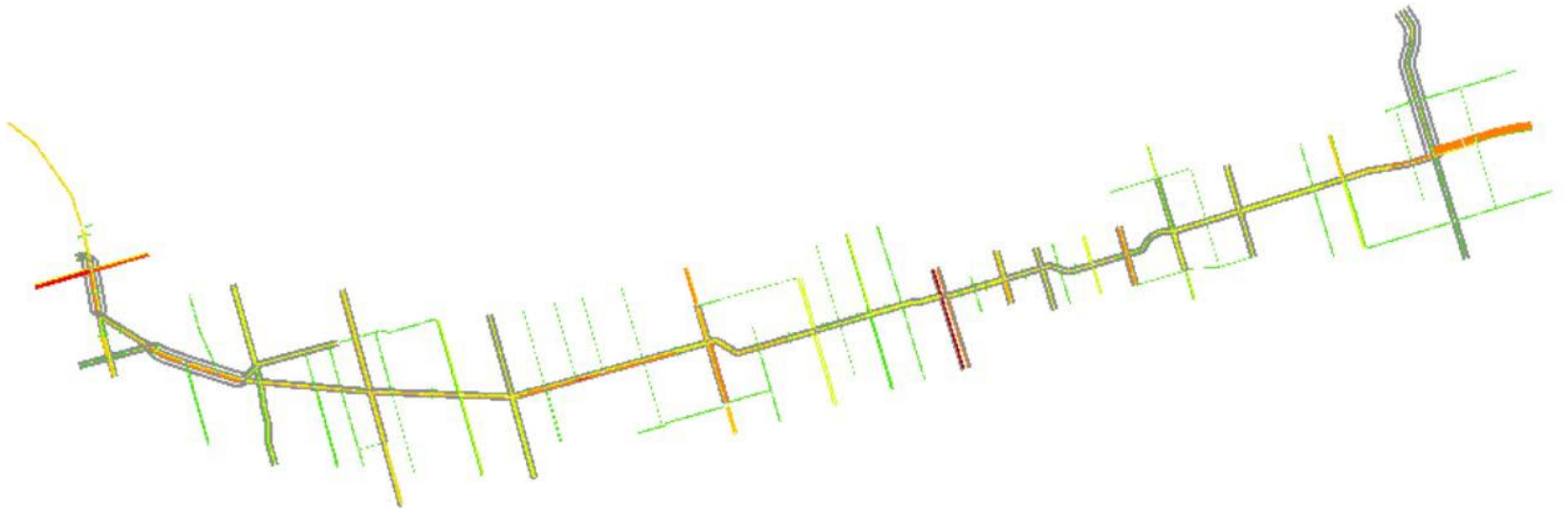


Northbound



Southbound

Simulation Video



Questions

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